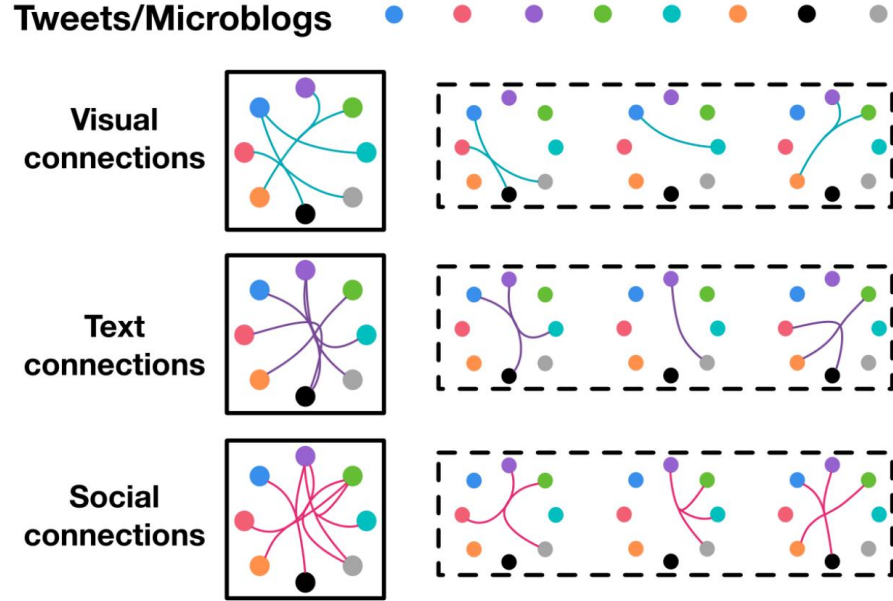


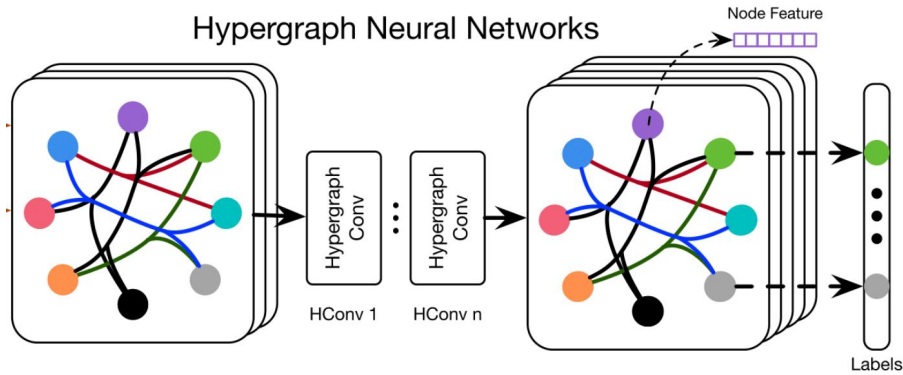
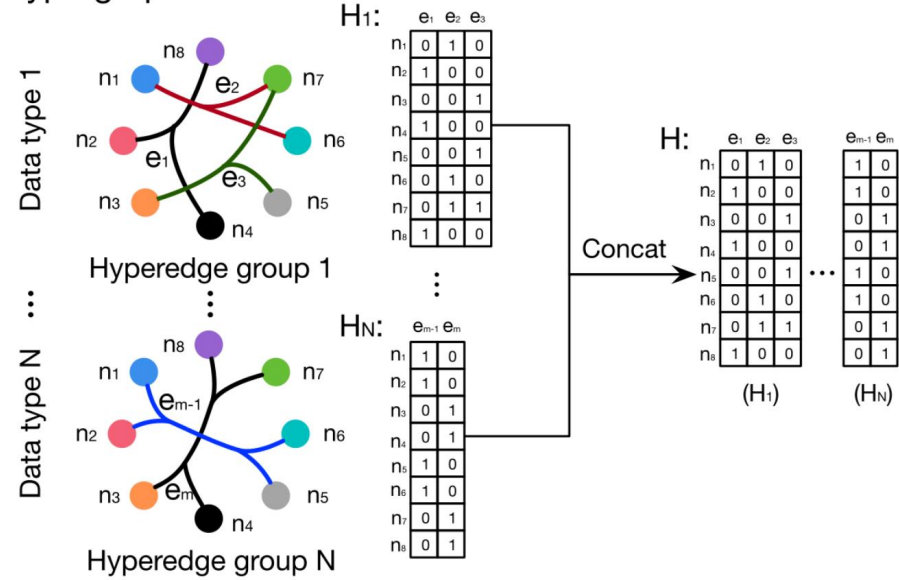
Hypergraph Neural Networks

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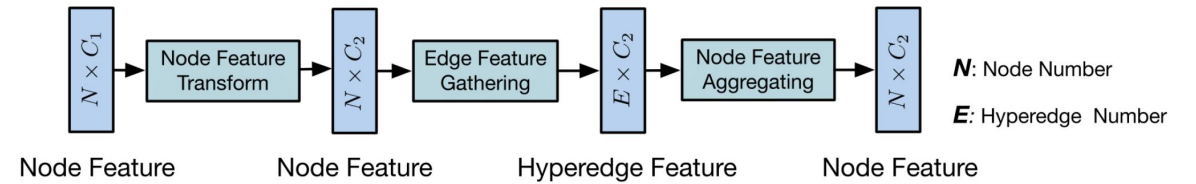
Framework



Hypergraph:



$$\mathbf{X}^{(l+1)} = \sigma(\mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{X}^{(l)} \Theta^{(l)})$$



Feature	Features for Structure					
	GVCNN		MVCNN		GVCNN+MVCNN	
	GCN	HGNN	GCN	HGNN	GCN	HGNN
GVCNN ((Feng et al. 2018))	78.8%	82.5%	78.8%	79.1%	75.9%	84.2%
MVCNN ((Su et al. 2015))	74.0%	77.2%	71.3%	75.6%	73.2%	83.6%
GVCNN+MVCNN	-	-	-	-	76.1%	84.2%

Table 5: Comparison between GCN and HGNN on the NTU dataset.

Graph Signal Processing

- Laplacian

$$L = D - A$$

$$\mathcal{L} = U\Lambda U^{-1} = U\Lambda U^T$$

- Graph Signal Variance

$$f^T L f = f^T D f - f^T W f = \sum_{i=1}^n D_{i,i} f_i^2 - \sum_{i,j} f_i f_j W_{i,j}$$

$$= \frac{1}{2} \left(\sum_{i=1}^n D_{i,i} f_i^2 - 2 \sum_{i=1}^n \sum_{j=1}^n f_i f_j W_{i,j} + \sum_{j=1}^n D_{j,j} f_j^2 \right)$$

$$= \frac{1}{2} \left(\sum_{i=1}^n \sum_{j=1}^n W_{i,j} (f_i - f_j)^2 \right) \geq 0$$

- Normalized Laplacian

$$\mathcal{L} = I - D^{-1} A$$

$$\mathcal{L} = D^{-1/2} L D^{-1/2} = I - D^{-1/2} W D^{-1/2},$$

- Incidence Matrix $\nabla \in \mathbb{R}^{|E| \times |V|}$

$$\nabla_{i,j} = \begin{cases} \nabla_{i,j} = -1 & \text{if } v_j \text{ is the initial vertex of edge } e_i \\ \nabla_{i,j} = 1 & \text{if } v_j \text{ is the terminal vertex of edge of } e_i \\ \nabla_{i,j} = 0 & \text{if } v_j \text{ is not in } e_i \end{cases}$$

$$\nabla \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \end{bmatrix} = \begin{bmatrix} f_4 - f_1 \\ f_1 - f_2 \\ f_2 - f_4 \\ f_4 - f_3 \\ f_5 - f_4 \\ f_3 - f_5 \end{bmatrix}$$

$$\nabla^T (\nabla f) = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \\ 1 & 0 & -1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} f_4 - f_1 \\ f_1 - f_2 \\ f_2 - f_4 \\ f_4 - f_3 \\ f_5 - f_4 \\ f_3 - f_5 \end{bmatrix} = \begin{bmatrix} 2f_1 - f_2 - f_4 \\ 2f_2 - f_1 - f_4 \\ 2f_3 - f_4 - f_5 \\ 4f_4 - f_1 - f_2 - f_3 - f_5 \\ 2f_5 - f_3 - f_4 \end{bmatrix}$$

$$\nabla^2 f = [f(x+1, y) + f(x-1, y) + f(x, y+1) + f(x, y-1)] - 4f(x, y)$$

$$L f = \nabla^T (\nabla f)$$

$$(L f)_i = \sum_{j=1}^n W_{i,j} (f_i - f_j),$$

Graph Signal Processing

- Graph Fourier Transform

$$\mathcal{F}[f(t)] = \int f(t)e^{-i\omega t} dt$$

$$\mathcal{F}[(f * g)(t)] = \mathcal{F}(f(t)) \odot \mathcal{F}(g(t))$$

$$(f * g)(t) = \mathcal{F}^{-1}[\mathcal{F}(f(t)) \odot \mathcal{F}(g(t))]$$

$$\mathcal{L} = U \Lambda U^{-1} = U \Lambda U^T$$

$$\mathcal{F}(\mathbf{f}) = \mathbf{U}^T \mathbf{f}$$

$$\mathcal{F}^{-1}(\hat{\mathbf{f}}) = \mathbf{U} \hat{\mathbf{f}}$$

- Graph Filter

$$\begin{aligned} \mathbf{f} *_{\mathcal{G}} \mathbf{g} &= \mathcal{F}^{-1}(\mathcal{F}(\mathbf{f}) \odot \mathcal{F}(\mathbf{g})) \\ &= \mathbf{U} (\mathbf{U}^T \mathbf{f} \odot \mathbf{U}^T \mathbf{g}) \\ &= \mathbf{U} (\hat{\mathbf{f}} \odot \hat{\mathbf{g}}) \\ &= \mathbf{U} \mathbf{g}_{\theta}(\Lambda) \mathbf{U}^T \mathbf{f} \end{aligned}$$

- Spectral CNN

$$g_{\theta_{i,j}}^{(k)} = \begin{bmatrix} \theta_1^{(k)} & & & \\ & \theta_2^{(k)} & & \\ & & \ddots & \\ & & & \theta_n^{(k)} \end{bmatrix}$$

$$f_j^{(k+1)} = \sigma \left(U \sum_{i=1}^{C_k} g_{\theta_{i,j}}^{(k)} U^T f_i^{(k)} \right) = \sigma \left(U \sum_{i=1}^{C_k} g_{\theta_{i,j}}^{(k)} \hat{f}_i^{(k)} \right)$$

- Spatial K-Localization

$$g_{\theta}(\Lambda) = \begin{pmatrix} \sum_{i=0}^K \theta_i \lambda_1^i & & \\ & \ddots & \\ & & \sum_{i=0}^K \theta_i \lambda_n^i \end{pmatrix} = \sum_{i=0}^K \theta_i \Lambda^i$$

$$\mathbf{f} *_{\mathcal{G}} \mathbf{g} = \mathbf{U} \left(\sum_{i=0}^K \theta_i \Lambda^i \right) \mathbf{U}^T \mathbf{f} = \sum_{i=0}^K \theta_i (\mathbf{U} \Lambda^i \mathbf{U}^T) \mathbf{f} = \sum_{i=0}^K \theta_i \mathbf{L}^i \mathbf{f}$$

Graph Signal Processing

- ChebNet

$$T_{n+1}(x) = 2xT_n(x) - T_{n-1}(x)$$

$$T_0(x) = 1, T_1 = x$$

$$\tilde{\Lambda} = \frac{2\Lambda}{\lambda_{max}} - I_n \in [-1, 1]$$

$$g_\theta(\Lambda) = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda})$$

$$g_\theta(\Lambda) = \begin{bmatrix} \hat{g}(\lambda_1) & & & \\ & \hat{g}(\lambda_2) & & \\ & & \ddots & \\ & & & \hat{g}(\lambda_n) \end{bmatrix}$$

$$= \begin{bmatrix} \sum_{k=0}^{K-1} \theta_k T_k(\hat{\lambda}_1) & & & \\ & \sum_{k=0}^{K-1} \theta_k T_k(\hat{\lambda}_2) & & \\ & & \ddots & \\ & & & \sum_{k=0}^{K-1} \theta_k T_k(\hat{\lambda}_n) \end{bmatrix}$$

$$g_\theta(\mathcal{L})f = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\mathcal{L}})f$$

$$\begin{aligned} f(\cdot_G)g_\theta &= g_\theta(U\Lambda U^T)f = U \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda})U^T f = \sum_{k=0}^{K-1} U \theta_k T_k(\tilde{\Lambda})U^T f \\ &= \sum_{k=0}^{K-1} U \theta_k \left(\sum_{c=0}^k \alpha_{kc} \tilde{\Lambda}^k \right) U^T f = \sum_{k=0}^{K-1} \theta_k \left(\sum_{c=0}^k \alpha_{kc} U \tilde{\Lambda}^k U^T \right) f \\ &= \sum_{k=0}^K \theta_k \left(\sum_{c=0}^k \alpha_{kc} (U \tilde{\Lambda} U^T)^k \right) f = \sum_{k=0}^{K-1} \theta_k T_k(U \tilde{\Lambda} U^T) f \\ &= \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\mathcal{L}})f. \end{aligned}$$

- Spectral CNN versus ChebNet

1. Eigenvector computation is time-consuming.
2. Learnable parameters need attention.
3. Laplace matrix maybe not eigen-decomposed.

Graph Signal Processing

- GCN

$$g_{\theta}(A) = \sum_{k=0}^1 \theta_k T_k(\tilde{A})$$

$$\tilde{\mathcal{L}} = \frac{2}{\lambda_{max}} \mathcal{L} - I_n = \mathcal{L} - I_n \quad \lambda_{max} \approx 2$$

$$\begin{aligned} f(\cdot_G)g &= \sum_{k=0}^1 \theta_k T_k(\tilde{\mathcal{L}})f = \theta_0 T_0(\tilde{\mathcal{L}})f + \theta_1 T_1(\tilde{\mathcal{L}})f \\ &= (\theta_0 + \theta_1(\mathcal{L} - I_n))f = (\theta_0 - \theta_1(D^{-\frac{1}{2}}AD^{\frac{1}{2}}))f \\ &= (\theta(D^{-\frac{1}{2}}AD^{-\frac{1}{2}} + I_n))f \quad \text{set } \theta_0 = -\theta_1 = \theta \end{aligned}$$

$$\tilde{A} = A + I_n$$

$$\tilde{D}_{i,i} = \sum_{j=1}^n \tilde{A}_{i,j}$$

$$f(\cdot_G)g = \theta \tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} f.$$

$$\hat{A} = \tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}}$$

$$Z = \text{softmax}(\hat{A} \text{ReLU}(\hat{A}fW^{<0>}))W^{<1>}$$

- Hypergraph Laplacian

$$\text{diag}(\mathbf{W}) = [w(e_1), w(e_2), \dots, w(e_{|\mathcal{E}|})]$$

$$\mathbf{H} \in \{0, 1\}^{|\mathcal{V}| \times |\mathcal{E}|} \quad \mathbf{H}(v, e) = \begin{cases} 1 & \text{if } v \in e \\ 0 & \text{if } v \notin e \end{cases}$$

$$\mathbf{D}_e \in \mathbb{R}^{|\mathcal{E}| \times |\mathcal{E}|} \quad \delta(e) = \sum_{v \in \mathcal{V}} \mathbf{H}(v, e)$$

$$\mathbf{D}_v \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{V}|} \quad d(v) = \sum_{e \in \mathcal{E}} w(e) * \mathbf{H}(v, e)$$

$$\Delta = \mathbf{D}_v - \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T$$

$$\Delta = \mathbf{I} - \mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2}$$

- Hypergraph Signal Variance

$$\Omega(\mathbf{F}) = \frac{1}{2} \sum_{e \in \mathcal{E}} \sum_{\{u,v\} \subseteq e} \frac{w(e)}{\delta(e)} \left(\frac{\mathbf{F}(u)}{\sqrt{d(u)}} - \frac{\mathbf{F}(v)}{\sqrt{d(v)}} \right)^2 = \mathbf{F}^T \Delta \mathbf{F}.$$

$$\underset{\mathbf{F}}{\text{argmin}} \Psi(\mathbf{F}) := \left\{ \mathbf{F}^T \Delta \mathbf{F} + \lambda \|\mathbf{F} - \mathbf{Y}\|^2 \right\}$$

Graph Signal Processing

- HyperGNN

$$\Delta = \Phi \Lambda \Phi^T$$

$$\mathbf{g} \star \mathbf{x} = \Phi((\Phi^T \mathbf{g}) \odot (\Phi^T \mathbf{x})) = \Phi g(\Lambda) \Phi^T \mathbf{x}$$

$$g(\Lambda) = \text{diag}(g(\lambda_1), \dots, g(\lambda_n))$$

$$\mathbf{g} \star \mathbf{x} \approx \sum_{k=0}^K \theta_k T_k(\tilde{\Delta}) \mathbf{x}$$

$$\mathbf{g} \star \mathbf{x} \approx \theta_0 \mathbf{x} - \theta_1 \mathbf{D}^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{x}$$

$$\begin{cases} \theta_1 = -\frac{1}{2}\theta \\ \theta_0 = \frac{1}{2}\theta \mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \end{cases}$$

$$\mathbf{g} \star \mathbf{x} \approx \frac{1}{2} \theta \mathbf{D}_v^{-1/2} \mathbf{H} (\mathbf{W} + \mathbf{I}) \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{x}$$

$$\approx \theta \mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{x},$$

$$\mathbf{X}^{(l+1)} = \sigma(\mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{X}^{(l)} \Theta^{(l)})$$

$$\begin{aligned} & \mathbf{f}^T (\mathbf{I} - \mathbf{D}_v^{-\frac{1}{2}} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-\frac{1}{2}}) \mathbf{f} \\ &= \mathbf{f}^T \mathbf{D}_v^{-\frac{1}{2}} (\mathbf{D}_v - \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T) \mathbf{D}_v^{-\frac{1}{2}} \mathbf{f} \quad (\mathbf{W} \mathbf{D}_e^{-1} = \tilde{\mathbf{W}} \quad \mathbf{D}_v^{-\frac{1}{2}} \mathbf{f} = \tilde{\mathbf{f}}) \\ &= \tilde{\mathbf{f}}^T (\mathbf{D}_v - \mathbf{H} \tilde{\mathbf{W}} \mathbf{H}^T) \tilde{\mathbf{f}} \\ &= \underbrace{\tilde{\mathbf{f}}^T \mathbf{D}_v \tilde{\mathbf{f}}}_{\mathcal{D}} - \underbrace{\tilde{\mathbf{f}}^T \mathbf{H} \tilde{\mathbf{W}} \mathbf{H}^T \tilde{\mathbf{f}}}_{\text{target}} \\ &= \frac{1}{2} \sum_e \sum_{uv} \tilde{w}_{(e)} h_{(u,e)} h_{(v,e)} (\tilde{f}_{(u)} - \tilde{f}_{(v)})^2 \\ &= \left(\sum_u h_{(u,e)} \tilde{f}_{(u)}, \dots, \sum_u h_{(u,e)} \tilde{f}_{(u)} \right) \begin{pmatrix} \tilde{w}_1 \sum_v h_{(v,e)} \tilde{f}_{(v)} \\ \vdots \\ \tilde{w}_n \sum_v h_{(v,e)} \tilde{f}_{(v)} \end{pmatrix} \\ &= \sum_e \sum_{uv} \tilde{w}_{(e)} h_{(u,e)} h_{(v,e)} \tilde{f}_{(u)} \tilde{f}_{(v)} \\ &\mathcal{D} = \sum_u \tilde{f}_{(u)}^2 \sum_e w_{(e)} h_{(u,e)} \\ &= \sum_{u,v} \sum_e \tilde{w}_{(e)} h_{(u,e)} h_{(v,e)} \tilde{f}_{(u)} \tilde{f}_{(v)} \quad \# \end{aligned}$$