

1. (b).  $\sigma'(x) = \sigma(x) \cdot (1 - \sigma(x))$

2. Ridge Reg:

$$J(\theta) = \|y - X\theta\|^2 + \lambda \|\theta\|^2$$

$$\begin{aligned} \nabla_{\theta} J(\theta) &= \nabla_{\theta} ( (y - X\theta)^T (y - X\theta) + \lambda \theta^T \theta ) \\ &= 2(X^T X + \lambda I)\theta - 2X^T y \end{aligned}$$

$$\theta^* = (X^T X + \lambda I)^{-1} X^T y$$

$$\theta_y^* = (X^T X)^{-1} X^T y$$

$$x = (f_1, f_2, f_1 + f_2)$$

$X^T X$  may not be invertible.

3. MAP, MLE

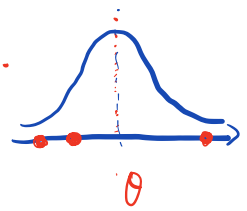
$$\rightarrow \theta_{MLE} = \operatorname{argmax}_{\theta} P(x_1, x_2, \dots, x_m | \theta)$$

$$= \operatorname{argmax}_{\theta} \prod_i^m P(x_i | \theta)$$

$$= \operatorname{argmax}_{\theta} \prod_i^m \left[ \frac{1}{\sqrt{2\sigma^2}} \cdot \exp\left\{ -\frac{(x_i - \theta)^2}{2\sigma^2} \right\} \right]$$

$$\log L = \sum_i^m \left( -\frac{1}{2} \log(2\lambda\sigma^2) - \frac{1}{2\sigma^2} (x_i - \theta)^2 \right)$$

$$\nabla_{\theta} L = 0 \Rightarrow \theta_{MLE} = \frac{1}{m} \sum_i^m x_i$$



$$P(\theta) \sim N(\mu, \sigma^2)$$

$$\rightarrow \theta_{MAP} = \operatorname{argmax}_{\theta} P(\theta | x_1, x_2, \dots, x_m)$$

$$= \operatorname{argmax}_{\theta} \frac{P(x_1, x_2, \dots, x_m | \theta) \cdot P(\theta)}{P(x_1, x_2, \dots, x_m)}$$

$$= \operatorname{argmax}_{\theta} \prod_i^m P(x_i | \theta) \cdot P(\theta)$$

$$\nabla_{\theta} \log Q = 0 \Rightarrow \theta_{MAP} = \mu + \sigma^2 \cdot \sum_{i=1}^m x_i \rightarrow \frac{\sum_{i=1}^m x_i}{n}$$

$$\sigma^2 + m\mu^2 \quad m \rightarrow \infty$$

4. Softmax Reg.

$$l(\theta) = \sum_i^m \sum_l^k \cdot \mathbb{1}\{y^i=l\} \cdot \log \frac{e^{\theta_l^T x^i}}{\sum_j e^{\theta_j^T x^i}}$$

$$\mathbb{1}\{y^i=l\} = \begin{cases} 1, & y^i=l \\ 0, & \text{o.w.} \end{cases}$$

$$l(\theta) = \underbrace{\log \frac{e^{\theta_{y_1}^T x^1}}{\Sigma}}_{1^{st}} + \underbrace{\log \frac{e^{\theta_{y_2}^T x^2}}{\Sigma}}_{2^{nd} \leftarrow y_2=1} + \dots + \log \frac{e^{\theta_{y_m}^T x^m}}{\Sigma}$$

$$= \log \cdot (e^{\theta_{y_1}^T x^1}) + \log (e^{\theta_{y_2}^T x^2}) + \dots + m \cdot \log(\Sigma)$$

$$= \sum_i^m \sum_l^k \cdot \mathbb{1}\{y^i=l\} \cdot \theta_l^T x^i + m \cdot \log \left( \sum_j e^{\theta_j^T x^i} \right)$$

$$\nabla_{\theta_l} l(\theta) = \sum_i^m \nabla_{\theta_l} \left( \sum_l^k \mathbb{1}\{y^i=l\} \theta_l^T x^i \right) \quad \log(f(x)) = \frac{f(x)}{f(x)}$$

$$= \sum_i^m \cdot (\mathbb{1}\{y^i=l\} \cdot x^i) + m \cdot \frac{e^{\theta_l^T x^i} \cdot x^i}{\Sigma}$$

5.  $\min_x f(x) \triangleq \|y - Ax\|^2$       $A_{m \times n}$       $m \ll n$   
 $x_0 = 0$      implicit bias.



$$\nabla_x f(x) = A^T(Ax - y)$$

$$x_{k+1} = x_k - 2\alpha \cdot A^T(Ax - y) = \underbrace{(I - 2\alpha A^T A)}_{x_0=0} \cdot x_k + \underbrace{2\alpha A^T y}_{x_1 = 2\alpha A^T y}$$

$$x_2 = (I + I - 2\alpha A^T A) \cdot 2\alpha A^T y$$

$$x_3 = (I + (I - 2\alpha A^T A) + (I - 2\alpha A^T A)^2) \cdot 2\alpha A^T y.$$

$$\vdots$$

$$x_{k+1} = 2\alpha \left( \sum_{t=0}^k (I - 2\alpha A^T A)^t \right) \cdot A^T y$$

$$\sum_{t=0}^{\infty} (1-q)^t = \frac{1}{q} \uparrow \quad A^T A \text{ may not be invertible.}$$

$$A = U \Sigma V^T = U \begin{bmatrix} \Sigma_1 & 0 \end{bmatrix} \begin{bmatrix} V_1^T \\ V_2^T \end{bmatrix} = U \Sigma_1 \cdot V_1^T.$$

$$2\alpha A^T A = V \Sigma^T \underline{U^T \cdot U} \Sigma V^T = V \Sigma^T \Sigma V^T \cdot 2\alpha.$$

$$(I - 2\alpha A^T A) = V V^T - V \Sigma^T \Sigma V^T \cdot 2\alpha = V [I - 2\alpha \Sigma^T \Sigma] V^T$$

$$(I - 2\alpha A^T A)^2 = V [I - 2\alpha (\Sigma^T \Sigma)] V^T \cdot V [\dots] V^T$$

$$= V [I - 2\alpha (\Sigma^T \Sigma)]^2 V^T$$

$$\text{So } (I - 2\alpha A^T A)^t = V [I - 2\alpha (\Sigma^T \Sigma)]^t \cdot V^T$$

$$x_{\infty} = 2\alpha \cdot V \left[ \sum_{t=0}^{\infty} (I - 2\alpha \underline{\Sigma^T \Sigma})^t \right] \cdot \underline{V^T \Sigma^T U^T} \cdot y$$

$$\Sigma_1 = \Sigma_1^T \quad \Sigma^T \Sigma = \begin{bmatrix} \Sigma_1 \\ 0 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \end{bmatrix} = \Sigma_1^2.$$

$$x_{\infty} = \underline{2\alpha} \cdot V \left( \underline{2\alpha} \Sigma_1^2 \right)^{-1} \cdot \Sigma^T \cdot U^T y.$$

∴ ... → ...

$$\begin{aligned} &= [v_1 \ v_2] \cdot \Sigma_1^{-1} \cdot \begin{bmatrix} z_1 \\ 0 \end{bmatrix} \cdot U y \\ &= \underline{v_1 \Sigma_1^{-1} U^T y} = \underset{\uparrow}{A^T (A A^T)^{-1}} y. \end{aligned}$$