Learning from Data Lecture 8: Unsupervised Learning I

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Today's Lecture

Unsupervised Learning (Part I)

- Overview: the representation learning problem
- K-means clustering
- Spectral clustering

Project Introduction

Clustering from a graph point of view

- Given data points $x^{(1)}, \ldots, x^{(n)}$ and similarity measure $s_{ij} \ge 0$ for all $x^{(i)}, x^{(j)}$
- A typical similarity graph G = (V, E) is
 - $v_i \leftrightarrow x^{(i)}$
 - v_i and v_j are connected if $s_{ij} \ge \delta$ for some threshold δ
- **Clustering**: Divide data into groups such that points in the same group are similar and points in different groups are dissimilar
 - **Spectral Clustering (informal)**: Find a partition of G such that edges between the same group have high weight and edges between different groups have very low weight.

Spectral Clustering as Graph Partitioning

Find a partition of the graph such that

- Edges between groups have a low weight
- Edges within each group have a high weight



Graph Cut Formulation

Case k = 2:

 Given partition A, A, define a cut as the total weight of edges weights between groups:



Graph Cut Formulations

Case k > 2:

• Given partition A_1, \ldots, A_k , define a cut as the total edges weights between groups:

$$\underline{cut}(A_1,\ldots,A_k) \coloneqq \frac{1}{2} \sum_{i=1}^k \underline{cut}(A_i) \overline{A_i})$$

Graph Cut Formulations

Case k > 2:

▶ Given partition A₁,..., A_k, define a cut as the total edges weights between groups:





Find a k-way partition of graph G ($A_i \cup \ldots \cup A_k = V, A_i \cap A_j = \emptyset$) that minimizes:

$$\underline{RatioCut}(A_{1}, \dots, A_{k}) = \frac{1}{2} \sum_{i=1}^{k} \frac{cut(A_{i}, \overline{A}_{i})}{|A_{i}|} \quad [\text{Hagen & Kahng, 1992}]$$
$$|A_{1}| = 3 \quad |A_{2}| = 3$$
$$\underline{NCut}(A_{1}, \dots, A_{k}) = \frac{1}{2} \sum_{i=1}^{k} \frac{cut(A_{i}, \overline{A}_{i})}{|vol(A_{i})|},$$
$$vol(A_{i}) = \sum_{i \in A, i \in V} w_{ij} \quad [\text{Shi & Malik , 2000}]$$

= Zdi icA

Balanced Graph Cut

RatioCut and NCut

Find a k-way partition of graph G ($A_i \cup \ldots \cup A_k = V, A_i \cap A_j = \emptyset$) that minimizes:

$$RatioCut(A_1,\ldots,A_k) = \frac{1}{2}\sum_{i=1}^k \frac{cut(A_i,\bar{A}_i)}{|A_i|} \quad [\text{Hagen \& Kahng,1992}]$$

$$\begin{aligned} \mathsf{NCut}(A_1,\ldots,A_k) &= \frac{1}{2}\sum_{i=1}^k \frac{\mathsf{cut}(A_i,\bar{A}_i)}{\mathsf{vol}(A_i)},\\ \mathsf{vol}(A_i) &= \sum_{i\in A, j\in V} \mathsf{w}_{ij} \text{ [Shi \& Malik ,2000]} \end{aligned}$$

Both RatioCut and NormalizeCut can be **approximated** by spectral method.



Unnormalized graph laplacian matrix:

L=D-W

Properties of L

• For every $f \in \mathbb{R}^n$, $f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2$



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- For every $f \in \mathbb{R}^n$, $f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i f_j)^2$
- L is symmetric and positive <u>semi</u>-definite $\forall f \in \mathbb{P}^{k}$, $f \downarrow f = \frac{1}{2} \sum_{j=1}^{k} W_{ij} (f; f_{j})^{k}$

Unnormalized graph laplacian matrix:

L=D-W

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- The smallest eigenvalue of \underline{L} is 0 with eigenvector $\mathbf{1}$

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- L is symmetric and positive semi-definite
- The smallest eigenvalue of L is 0 with eigenvector ${f 1}$
- *L* has *n* real eigenvalues $0 = \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$

A Review on Eigenvalue Problem

The Eigenvalue Problem

Nonzero vector $\underline{u} \in \mathbb{R}^n$ is an **eigenvector** of matrix $\underline{A} \in \mathbb{R}^{n \times n}$ if

$$Au = \lambda u$$

for some $\lambda \in \mathbb{R}$. We call λ the **eigenvalue** corresponding to u.

• A has at most *n* distinct eigenvalues

Eigenvalue Decomposition

Rayleigh-Ritz Theorem

Theorem 1

Given symmetric matrix $\underline{A \in \mathbb{R}^{n \times n}}$, the solution to the minimization problem is the smallest eigen vector of A

$$\underbrace{\min_{x \in \mathbb{R}^n} x^T A_x}_{s.t. ||x||^2 = 1} \stackrel{\min_{x \in \mathbb{R}^n} x^T A_x}{st. x^T x - 1 = 0}.$$
(1)

• An equivalent form of (1) is minimizing the **Rayleigh quotient**
$$\frac{x^{T}Ax}{x^{T}x}$$

• Scale x by some C
• scale that $\|x\|^{5-1}$.
 $x \neq 0 \in \mathbb{R}^{n}$ $\frac{x^{T}Ax}{x^{T}x}$ $\left[L(x) = \underline{x^{T}Ax} + \beta(x^{T}x^{-1}) - \beta(x^{T}x^$

Rayleigh-Ritz Theorem

X1 X2-- XK Generalization to multiple vectors: Theorem 2 (nxk) |Xil= kEn Given symmetric matrix $A \in \mathbb{R}^{n \times n}$, $\vec{x} = [x_1, \dots, x_k], x_i \in \mathbb{R}^n$, the solution to the minimization problem are k smallest eigen vector of A: $\min_{X \in \mathbb{R}^{n \times k}} tr(X^T A X)$ (2) $\begin{array}{c} \text{MIN} \quad \begin{array}{c} \textbf{k} \\ \textbf{x}_{1} \\ \textbf{x}_{2} \\ \textbf{x}_{2} \\ \textbf{x}_{k} \\ \textbf{x}_$ st. $x_i^T x_j = 1$ of i = j \longrightarrow lo of $i \neq j \rightarrow x_i \perp x_j$

Unnormalized graph laplacian matrix:

L = D - W

Properties of L • The smallest eigenvalue of L is 0 with eigenvector 1 L = (D - W) = D - W = D - D = 0 - 1. Since L is positive semi-definite. =) $\lambda_i \ge 0$ for all eigenvalues λ_i i = b - 2h.

Unnormalized graph laplacian matrix:

L = D - W

- The smallest eigenvalue of L is 0 with eigenvector $\mathbf{1}$
- L has n real eigenvalues $0 = \lambda_1 \leq \lambda_2 \leq \ldots \leq \lambda_n$



2) When K71, G has k connected components A. Ak. L= Li Where each Li is the laplacian of A: [Lz]
[Lk] For a block diagonal L, eigenvalues of L are unions of LI, ..., LK, whose eigenvectors are eigenvectors of Li with D tilled in other blocks. let lij, fij be jth eigenvalue, eigenvector of Li $L \begin{bmatrix} U \\ T_{i} \end{bmatrix} = \begin{bmatrix} 0 \\ L_{i} \\ V_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \\ \overline{V}_{ij} \end{bmatrix} = \lambda_{ij} \begin{bmatrix} 0 \\ \overline{V}_{ij} \end{bmatrix} =$ [vij] is an eigenvector of L. (K= ?) Each Li has eigenvalue O with multiplicity 1, Therefore, L has total multiplicity k, its eigenvectors are spanned by 11A:. \square_{-}

unnormalized graph laplacian

L = D - W.

Properties of L_{rw}

(Normalized) Graph Laplacian

Normalized graph laplacian (Chung 1997) ¹:

$$L_{rw} = \underbrace{D^{-1}L}_{(\mathbf{b}-\mathbf{w})} = I - D^{-1}W$$

- λ is an eigenvalue of L_{rw} with eigenvector v if and only if λ , v solve the generalized eigenproblem $Lv = \lambda Dv$
- \triangleright 0 is an eigenvalue of $l_{
 m r}$ with eigenvector 1
- L_{rw} is positive semi-definite and has *n* non-negative eigenvalues $0 = \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$

 $^1"rw"$ comes from its interpertation as "random walk". Another definition of normalized graph Laplacian is $D^{-\frac{1}{2}}LD^{-\frac{1}{2}}$

(Normalized) Graph Laplacian

Normalized graph laplacian (Chung 1997) ¹:

$$L_{rw} = D^{-1}L = I - D^{-1}W$$

Properties of L_{rw}

- λ is an eigenvalue of L_{rw} with eigenvector v if and only if λ , v solve the generalized eigenproblem $Lv = \lambda Dv$
- \blacktriangleright 0 is an eigenvalue of L with eigenvector ${\bf 1}$
- L_{rw} is positive semi-definite and has *n* non-negative eigenvalues $0 = \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$

Proposition 2

Let G be an undirected graph with non-negative weights W, the multiplicity <u>k</u> of eigenvalue 0 of L_{rw} is the number of connected components A_1, \ldots, A_k in G. The eigenspace of eigenvalue 0 is spanned by vectors $\mathbf{1}_{A_1}, \ldots, \mathbf{1}_{A_k}$

 $^1"rw"$ comes from its interpertation as "random walk". Another definition of normalized graph Laplacian is $D^{-\frac{1}{2}}LD^{-\frac{1}{2}}$

AL- AK.

Define $f \in \{0,1\}^n$ to be the indicator function for partition $A \subset V$: $f_{i} := \{\mathbf{1}_{A}\}_{i} = \begin{cases} 1 & v_{i} \in A \\ 0 & v_{i} \in \overline{A} \end{cases}$ We have that $||f||^{2} = |A|$. $||f||^{2} = \sum_{i=1, i \in A}^{n} f_{i}^{*} = f_{i}^{*}$ $(f)^{T}Lf = \frac{1}{2}\sum_{i,j=1}^{n} \frac{w_{ij}(f_{i} - f_{j})^{2}}{(v_{i} \in A, v_{j} \in A)} = \frac{1}{2}\sum_{i,j=1}^{n} \frac{w_{ij}(f_{i} - f_{j})^{2}}{(v_{i} \in A, v_{j} \in A)}$ $= \frac{1}{2} \left(\sum_{v_i \in A, v_i \in \bar{A}} \underline{w_{ij}} + \sum_{v_i \in \bar{A}, v_j \in A} \underline{w_{ij}} \right) = \sum_{v_i \in A, v_j \in \bar{A}} \underline{w_{ij}} = cut(A, \bar{A})$ Let $f_{(1)}, \ldots, f_{(k)}$ be k indicator functions $\mathbf{1}_{A_i}, \ldots, \mathbf{1}_{A_k}$. They are mutually orthogonal (i.e. $f_{(i)}^T f_{(i)} = 0$ for all $i \neq j$).

Solving graph cut

s.t. $f_{(i)}^T f_{(j)} = 0$, for all $i \neq j$

Solving graph cut

Since rescaling $f_{(i)}$ by constants does not change the objective, (3) is equivalent to

$$\min_{f_{(1)},...,f_{(k)} \in \mathbb{R}^{n}} \sum_{i}^{k} f_{(i)}^{T} L f_{(i)}$$
s.t. $f_{(i)}^{T} f_{(j)} = 0$, for all $i \neq j$
 $f_{(i)}^{T} f_{(i)} = 1$, for all $i = 1, ..., k$
(6)

• By Theorem 2, optimal solution F^* is the first k eigenvectors of L.

To get discrete cluster labels, we can apply k-means clustering on the rows of F*.

Spectral Clustering Algorithm

Unormalized spectral clustering

Input: data points $x^{(1)}, \ldots, x^{(n)}$ and cluster size k

- \blacktriangleright Build a graph connecting $x^{(1)}, \ldots, x^{(n)}$ with weight W
- Compute first k eigenvectors $V = [v_1, \ldots, v_k]$ of L
- Define $y_i \in \mathbb{R}^k$ as the ith row of V, cluser y_1, \ldots, y_n into k clusters C_1, \ldots, C_k using k-means

Output: A_1, \ldots, A_k where $A_j = \{j | y_j = C_i\}$

 Unormalized spectral clustering is relaxed solution to the RatioCut problem.

Spectral Clustering Algorithm

Normalized spectral clustering (Ng, Shi and Malik 2000)

Input: data points $x^{(1)}, \ldots, x^{(n)}$ and cluster size k

- Build a graph connecting $x^{(1)}, \ldots, x^{(n)}$ with weight W
- Compute first k eigenvectors $V = [v_1, ..., v_k]$ of generalized eigen problem $Lv = \lambda Dv$
- Define $y_i \in \mathbb{R}^k$ as the ith row of V, cluser y_1, \ldots, y_n into k clusters C_1, \ldots, C_k using k-means

Output: A_1, \ldots, A_k where $A_i = \{j | y_j = C_i\}$

• Normalized spectral clustering (L_{rw}) is a relaxed solution to the <u>NCut</u> problem. <u> K_{i} </u> M_{i} (A; <u>A</u>; <u>A</u>; <u>)</u> M_{i} (A; <u>A</u>; <u>)</u>

Toy Example

- 200 data points sampled from 4 Gaussian distributions
- KNN similarity graph (k = 10)





First eigenvector is 1 since the graph has only 1 connected component

K-Means Clustering

Spectral Embedding

Also known as Laplacian Eigenmaps [Belkin et. al., 2003]:

• Learn a k-dimensional embedding $Y = \begin{bmatrix} -y_1 - \\ \vdots \\ -y_m - \end{bmatrix} \in \mathbb{R}^{n \times k}$



Spectral Embedding

Example: 2D embedding results:

- N: number of neighbors in kNN graph
- *t*: hyperparameter in the similarity function $W_{i,j} = \exp(\frac{||x_i-x_j||^2}{t})$



Additional topics of graph Laplacian methods



Graph spectra can be used as topological features for supervised and unsupervised learning

- Laplacian eigenmaps for dimension reduction and visualization
- Unsupervised segmentation
- Graph-based semi-supervised learning



Unsupervised segmentation using NCut [Shi & Malik, 2000]



Lazy Snapping (semi-supervised graph cut) [Li et. al. 2004]

	Unsupervised Learning Overview		K-Means Clustering		Spectral Graph Theo
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Summary

Representation learning

- Transform input features into "simpler" or "interpretable" representations.
- Used in feature extraction, dimension reduction, clustering etc