Learning From Data Lecture 4: Generative Learning Algorithms

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Introduction

Today's Lecture

Supervised Learning (Part III)

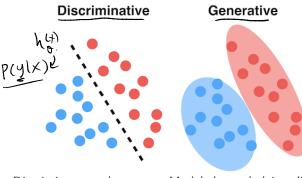
- Discriminative & Generative Models
- Gaussian Discriminant Analysis

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Discriminative & Generative Models

Two Learning Approaches



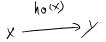


Discriminate between classes of data points

Model the underlying distribution of the data

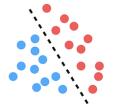
P(K, y)

Naïve Bave



Discriminative Learning Algorithms

A class of learning algorithms that try to learn the **conditional probability** p(y|x) directly or learn mappings directly from \mathcal{X} to \mathcal{Y} .



▶ e.g. linear regression, logistic regression, k-Nearest Neighbors ...

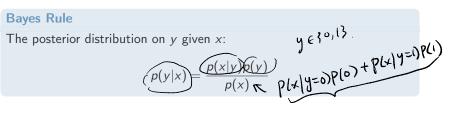
Generative Learning Algorithms

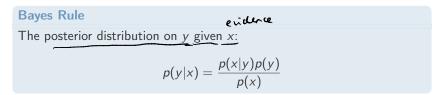
A class of learning algorithms that model the joint probability p(x, y) = p(x|y)P(y)



- Equivalently, generative algorithms model p(x|y) and p(y)
- \triangleright p(y) is called the **class prior**
- Learned models are transformed to p(y|x) later to classify data using Bayes' rule

Bayes Rule





Make predictions in a generative model:

$$\operatorname{argmax}_{y} p(y|x) = \operatorname{argmax}_{y} \left(\frac{p(x|y)p(y)}{p(x)c} \right)_{doesn't} depend on$$
$$= \operatorname{argmax}_{y} p(x|y)p(y)$$

No need to calculate p(x).

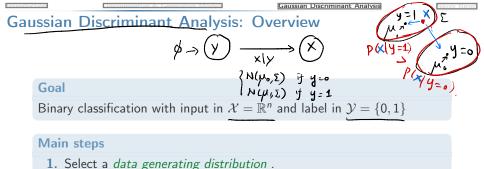
Generative Models

Generative classification algorithms:

Continuous input: Gaussian Discriminant Analysis (GPA)
 Discrete input: Naïve Bayes

Naïve Bave

Gaussian Discriminant Analysis



$$y \sim \underbrace{Bernoulli(\phi)}_{x|y=0} \begin{array}{l} p(y) \\ x|y=0 \sim N(\mu_0, \Sigma), x|y=1 \sim N(\mu_1, \Sigma) \end{array}$$

2. Estimate model parameters φ, μ₀, μ₁ and Σ from training data. P(X, Y)
 3. For any new sample x', predict its label by computing p(y|x = x'; φ, μ₀, μ₁, Σ)

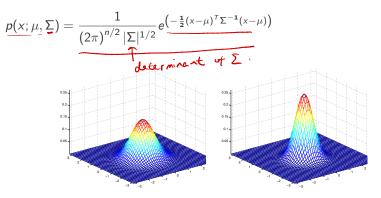
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Multivariate Normal Distribution

Multivariate normal (or multivariate Gaussian) distribution $N(\mu, \Sigma)$

- $\mu \in \mathbb{R}^n$ is the mean vector,
- $\Sigma \in \mathbb{R}^{n \times n}$ is the covariance matrix. Σ is symmetric and SPD.

Density function:

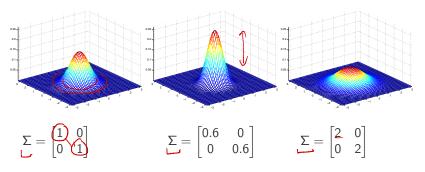


Multivariate Normal Distribution

Let $X \in \mathbb{R}^n$ be a random vector. If $X \sim N(\mu, \Sigma)$,

$$\mathbb{E}[X] = \int_{x} p(x; \mu, \Sigma) dx = \mu$$
$$Cov(X) = \mathbb{E}\left[(X - \mathbb{E}[X])(X - \mathbb{E}[X])^{T} \right] = \Sigma$$

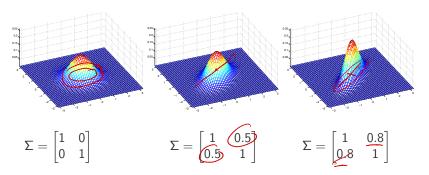
Gaussian Discriminative Analysis



Diagonal entries of $\boldsymbol{\Sigma}$ controls the "spread" of the distribution



Gaussian Discriminative Analysis



The distribution is no longer oriented along the axes when off-diagonal entries of $\boldsymbol{\Sigma}$ are non-zero.

p(x1 y= y) ~ N(my; E)

Gaussian Discriminant Analysis (GDA) Model

Given parameters $\phi, \mu_0, \mu_1, \Sigma$,

$$\begin{array}{c} \underline{y} \sim \text{Bernoulli}(\phi) \\ x|y = 0 \sim \mathcal{N}(\mu_0, \Sigma) \\ x|y = 1 \sim \mathcal{N}(\mu_1, \Sigma) \end{array} \right\}$$

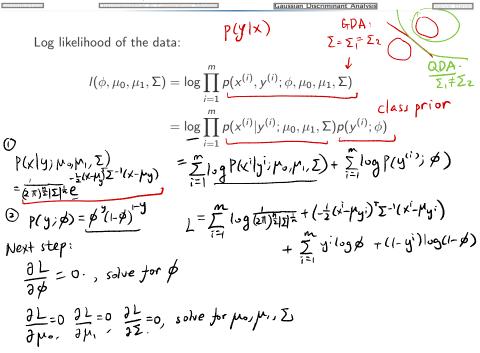
Probability density functions:

$$p(x|y = 0) = \frac{p(y) = \phi^{y}(1 - \phi)^{1 - y}}{(2\pi)^{n/2} |\Sigma|^{1/2}} e^{\left(-\frac{1}{2}(x - \mu_{0})^{T} \Sigma^{-1}(x - \mu_{0})\right)}$$

$$p(x|y = 1) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} e^{\left(-\frac{1}{2}(x - \mu_{1})^{T} \Sigma^{-1}(x - \mu_{1})\right)}$$

0.15

0.1



 $L = \sum_{i=1}^{m} \log \frac{1}{(2\pi)^{2} 12^{\frac{1}{2}}} + \left(-\frac{1}{2}(x^{2}-\mu_{y})^{2}\Sigma^{-1}(x^{2}-\mu_{y})\right) + \sum_{i=1}^{m} y^{i} \log \phi + (1-y^{i}) \log(1-\phi)$

 $\frac{\partial L}{\partial \beta} = \sum_{i=1}^{n} y^{(i)} \frac{\partial}{\partial \beta} \log \beta + (1 - y^{i}) \frac{\partial}{\partial \beta} \log(1 - \beta)$ $= \left(\sum_{i=1}^{m} \frac{y^{(i)}}{\varphi}\right) + \frac{(1-y^{(i)})}{1-\varphi}(-1)$ $= \frac{1}{p} \sum_{i=1}^{m} y^{(i)} - \frac{1}{1-p} \sum_{i=1}^{m} (1-y^{(i)})$ $C = \left[\begin{array}{c} \# \text{ of } 1^{(j)} \text{ in } \\ \text{training data} \end{array} \right] = \sum_{j=1}^{m} 1^{j} y^{(j)} = 1 \right\}.$ Facts $=\frac{c}{\phi}-\frac{m-c}{1-\phi}=0$ $\overline{\mathbb{O}}_{\mathbf{V}_{\mathbf{X}}}(\mathbf{x}^{\mathsf{T}}\mathbf{A}\mathbf{x})$ $c(1-\beta) = \beta(m-c)$ = Ax + A+x $(-c\phi - \phi(m-c) = 0.$ $c - \phi(c+m-c) = 0$ $\phi = \frac{c}{m} = \frac{1}{m} \sum_{i=1}^{m} (y^{i,i}) = 1)$ A is symmetric = ZAX $\frac{\partial L}{\partial \mu_{o}} = \sum_{i=1}^{m} \nabla_{\mu_{o}} - \frac{1}{2} (x^{i} - \mu_{o})^{T} \sum_{i=1}^{-1} (x^{i} - \mu_{o})$ X.=0 $= \sum_{i=1}^{m} -\frac{1}{2} \cdot 2 \sum_{i=1}^{n} (x^{i} - \mu_{\bullet}) (-1) \sum_{i=1}^{n} \sum_{i=1}^{n} (x^{$ $= \sum_{i=1}^{m} \sum_{j=1}^{-1} (x_{j}^{i} - \mu_{o}) = 0 \Rightarrow \sum_{i=1}^{m} (x_{i}^{i} - \mu_{o}) = 0.$ $\sum_{i=0}^{\infty} \frac{1}{1} \frac{1}{2} \frac{1}{2} = 0$ μ. = = 11 yi = 03 xii) 2 mean of 21191=03 $\frac{\partial \mathcal{L}}{\partial \mu_{1}} = 0 \implies \mu_{1} = \underbrace{\sum_{i=1}^{m} \mathcal{L}_{i} y^{i} = 1}_{\sum_{i=1}^{m} \mathcal{L}_{i} y^{i} = 1}$

$$L = \int_{1}^{\infty} \log \frac{1}{(2\pi)^{3}} \frac{1}{(2\pi)^{3}} + \left(-\frac{1}{2} (\delta^{2} - h_{y}^{2})^{3} \Sigma^{-1} (\delta^{2} - h_{y}^{2})\right) \\ + \int_{1}^{\infty} \frac{1}{(2\pi)^{3}} \frac{1}{(2\pi)^{3}$$

Log likelihood of the data:

$$\begin{split} l(\phi, \mu_0, \mu_1, \Sigma) &= \log \prod_{i=1}^m p(x^{(i)}, y^{(i)}; \phi, \mu_0, \mu_1, \Sigma) \\ &= \log \prod_{i=1}^m p(x^{(i)} | y^{(i)}; \mu_0, \mu_1, \Sigma) p(y^{(i)}; \phi) \end{split}$$

Log likelihood of the data:

$$\begin{split} l(\phi, \mu_0, \mu_1, \Sigma) &= \log \prod_{i=1}^m p(x^{(i)}, y^{(i)}; \phi, \mu_0, \mu_1, \Sigma) \\ &= \log \prod_{i=1}^m p(x^{(i)} | y^{(i)}; \mu_0, \mu_1, \Sigma) p(y^{(i)}; \phi) \end{split}$$

Maximum likelihood estimate of the parameters:

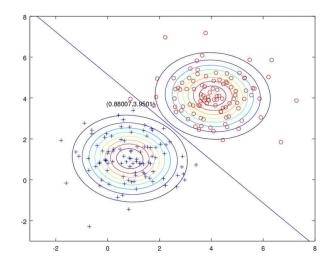
$$\phi = \frac{1}{m} \sum_{i=1}^{m} \mathbf{1} \{ y^{(i)} = 1 \}$$

$$\mu_b = \frac{\sum_{i=1}^{m} \mathbf{1} \{ y^{(i)} = b \} x^{(i)}}{\sum_{i=1}^{m} \mathbf{1} \{ y^{(i)} = b \}} \text{ for } b = 0, 1$$

$$\Sigma = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu_{y^{(i)}}) (x^{(i)} - \mu_{y^{(i)}})^T$$

Maximum likelihood estimation of GDA

GDA finds a linear decision boundary at which p(y = 1|x) = p(y = 0|x) = 0.5



Proposition

 $p(y = 1 | x; \phi, \mu_0, \mu_1, \Sigma)$ can be written in the form:

$$p(y = 1 | x; \phi, \Sigma, \mu_0, \mu_1) = \frac{1}{1 + e^{-\theta^T x}}$$

Proposition

 $p(y = 1 | x; \phi, \mu_0, \mu_1, \Sigma)$ can be written in the form:

$$\begin{aligned}
\rho(y = 1 | x; \phi, \Sigma, \mu_{0}, \mu_{1}) &= \frac{1}{1 + e^{\frac{\theta}{\theta}}} \\
\theta &= \begin{bmatrix} \theta_{1} \end{bmatrix}_{\Theta_{0}}^{\Theta_{0}} \begin{bmatrix} \Sigma^{-1}(\mu_{1} - \mu_{0}) \\ \frac{1}{2}(\mu_{0}^{T} \Sigma^{-1} \mu_{0} - \mu_{1}^{T} \Sigma^{-1} \mu_{1}) - \log \frac{1 - \phi}{\phi} \end{bmatrix}, x = \begin{bmatrix} x_{1} \\ \vdots \\ x_{n} \\ 1 \end{bmatrix} \\
p(y = 1 | x; H) &= \underbrace{P(x | y = 1; H) P(y = 1; H)}_{P(x; H)} = \underbrace{P(x | y = 1; H) P(y = 1; H)}_{P(x | y = 0; H) P(y = 1; H) + H} \\
&= \underbrace{1 + exp(-(\mu_{1} - \mu_{0}) \Sigma_{X}^{-1} - (\frac{1}{2}(\mu_{0}^{-\pi} \Sigma^{-1} \mu_{0} - \mu_{1}^{T} \Sigma^{-1} \mu_{1}) - \log \frac{1 - \phi}{\theta}}_{\theta_{1} + exp} \end{aligned}$$

Proposition

 $p(y = 1 | x; \phi, \mu_0, \mu_1, \Sigma)$ can be written in the form:

$$p(y = 1 | x; \phi, \Sigma, \mu_0, \mu_1) = \frac{1}{1 + e^{-\theta^T x}}$$

$$\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} \Sigma^{-1}(\mu_1 - \mu_0) \\ \frac{1}{2}(\mu_0^T \Sigma^{-1} \mu_0 - \mu_1^T \Sigma^{-1} \mu_1) - \log \frac{1 - \phi}{\phi} \end{bmatrix}, x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \\ 1 \end{bmatrix}$$

Similarly,

$$p(y=0|x;\phi,\Sigma,\mu_0,\mu_1)=rac{1}{1+e^{ heta^ au x}}$$

If $p(x|y) \sim \mathcal{N}(\mu, \Sigma)$, p(y|x) is a logistic function.



- Maximizes the **joint likelihood** $\prod_{i=1}^{m} p(x^{(i)}, y^{(i)})$
- Modeling assumptions: $x|y=b \sim \mathcal{N}(\mu_b, \Sigma), y \sim \text{Bernoulli}(\phi) \mathcal{P}(\mathcal{G})$
- When modeling assumptions are correct, GDA is asymptotically efficient and data efficient

Logistic Regression

- Maximizes the conditional likelihood $\prod_{i=1}^{m} p(y^{(i)}|x^{(i)})$
- Modeling assumptions: p(y|x) is a logistic function; no restriction on p(x)
- More robust and less sensitive to incorrect modeling assumptions.



Naïve Bayes: Motivating Example

A simple generative learning algorithm for discrete input variables

Example: Spam filter (document classification)

Classify email messages \underline{x} to spam (y = 1) and non-spam (y = 0) classes.

Hello

We need to confirm your info...

(1) FINAL MESSAGE: Payout Verification - \$3000 PAYOUT is ready to be addressed in your Name and we want to be sure it gets to the right place. Click below to start the confirmation process. The sooner you act, the sooner it can be in your hands!

Raging Bull Casino

A sample spam email

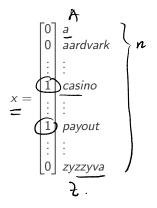
Example: Spam Filter

Binary text features

Given a dictionary of size \underline{n} , represent a message composed of dictionary words as $x \in \{0, 1\}^n$:

 $(x_i) = \begin{cases} 1 \\ 0 \end{cases}$

i-th dictionary word is in message otherwise



Naïve Bayes Model p(y) P(k(y))

Probability of observing email x_1, \ldots, x_n given spam class y :

$$p(x_1,...,x_n|y) = p(x_1|y)p(x_2|y,x_1),...,p(x_n|y,x_1,...,x_{n-1})$$

Naïve Bayes (NB) assumption

$$x_i$$
's are conditionally independent given y :
 $p(x_i|y, x_1, ..., x_{i-1}) = p(x_i|y)$
 $p(x_i|y) = p(x_1|y)p(x_2|y) ... p(x_n|y) = \prod_{i=1}^{n} p(x_i|y)$
 $f(x_i|y) = p(x_1, ..., x_n|y) = p(x_1|y)p(x_2|y) ... p(x_n|y) = \prod_{i=1}^{n} p(x_i|y)$

Naïve Baves

Naïve Bayes Parameters

Multi-variate Bernoulli event model x y generated from n independent Bernoulli trials $p(x, y) = p(y)p(x|y) = p(y) \prod p(x_i|y)$ $(y) \sim Bernoulli(\phi_y)$: assume email class (spam vs no-spam) is randomly generated with prior $p(y) = \phi_y^y (1 - \phi_y)^{1-y}$ $(x_i)y = b \sim Bernoulli(\phi_i|_{y=b}), b = 1, 2$: given y = b, each word x_i is included in the message independently with $p(x_i = 1|y = b) = \phi_{i|y=b}$ i.e. (1, 6) $p(x_i = 0|y=0) = \phi_{i|y=0}$ $p(x_i|y = b) = \phi_{i|y=b}^{x_i} (1 - \phi_{i|y=b})^{1-x_i}$ Model parameters:

$$\overrightarrow{\phi_{y}} \stackrel{\bullet}{} \underbrace{1}_{\phi_{i|y=1}, \phi_{i|y=0}} \text{ for } i=1,\ldots,n \quad 2n.$$

Naïve Bayes Parameter Learning

Likelihood of training data
$$(x^{(1)}, y^{(1)}), \dots, (x^{(m)}, y^{(m)})$$
: (...d
 $\mathcal{L}(\Theta)$
 $\mathcal{L}(\Theta)$
 $\mathcal{L}(\phi_y, \phi_{j|y=0}, \phi_{j|y=1}) = \prod_{i=1}^{m} p(x^{(i)}, y^{(i)})$ $(f) = p(x^{(i)}, y^{(i)}) p(y^{(i)})$
 $\mathcal{L}(\phi_y, \phi_{j|y=0}, \phi_{j|y=1}) = (f)$

Maximum likelihood estimation of parameters:

Naïve Bayes Prediction

$$(k_1, \ldots, k_n)$$

Given new example with feature x, compute the posterior probability

$$\underbrace{p(y=1|x)}_{\text{Assumption}} = \frac{p(x|y=1)p(y=1)}{\frac{p(x)}{p(x)}} \quad \text{trover } \phi_{y}^{*}, \rho_{i}|y=1}_{=} \\
= \frac{\frac{p(x|y=1)p(y=1)}{p(x|y=1)p(y=1)}}{\prod_{i=1}^{n} p(x_{i}|y=1)p(y=1)} \\
= \frac{\frac{p(x|y=1)p(y=1)}{p(x|y=1)p(y=1) + p(x|y=0)p(y=0)}}{\prod_{i=1}^{n} p(x_{i}|y=1)p(y=1) + \prod_{i=1}^{n} p(x_{i}|y=0)p(y=0)}$$

Choose label y = 1 (spam) if p(y = 1|x) > T where $T \in [0, 1]$ is a threshold ... e.g. T = 0.5 T tradeoff between wrongly blocked non-spam (FPs) vs. wrongly blocked spams (FNs). false negatives. false negatives.

Laplace smoothing

Issue with Naïve Bayes prediction:

Suppose word x_j hasn't been seen in the training data, $\phi_{i|y=1} =$ For all i=1,..., m, $1 + x_{j}^{(b)} = 1 = 0$ $\phi_{j} + y = b = \sum_{i=1}^{\infty} 1 + y' = b, x_{j}^{(b)} = 1 + \frac{1}{2} = 0$ $= \sum_{i=1}^{\infty} 2 + y' = b, x_{j}^{(b)} = 1 + \frac{1}{2} = 0$ $\int (\phi_{j} | y=1) = 0$ for the point of the

Laplace smoothing

Issue with Naïve Bayes prediction:

- Suppose word x_j hasn't been seen in the training data, $\phi_{j|y=1} = \phi_{j|y=0} = 0$
- Can not compute class posterior $p(y = 1|x) = \frac{0}{0}$.

Laplace smoothing

Issue with Naïve Bayes prediction:

Suppose word x_i hasn't been seen in the training data, $\phi_{i|y=1} = \phi_{i|y=0} = 0$

► Can not compute class posterior $p(y = 1|x) = \frac{0}{0}$. $\phi_j = \frac{1}{2}\sum_{i=1}^{\infty} \frac{1}{2} \sum_{i=1}^{\infty} \frac{1}{2} \sum_{i=1}^{\infty}$

Laplace smoothing

Let $z \in \{1, \ldots, k\}$ be a multinomial random variable. Given m independent observations $z^{(1)} \dots z^{(m)}$, maximum likelihood estimation of $\phi_i = p(z = i)$ with Laplace smoothing is Σ**¢**j=1, $\phi_j = \underbrace{\sum_{i=1}^m 1\{z^{(i)} = j\}}_{(m+k)} + \underbrace{1}_{t}$

•
$$\phi_i \neq 0$$
 for all *j*

$$\blacktriangleright \sum_{j=1}^k \phi_j = 1$$

Naïve Bayes with Laplace smoothing

Apply Laplace smoothing to $\phi_{j|y=b}$ for $b\in\{0,1\}$

$$\phi_{j|y=b} = \frac{\sum_{i=1}^{m} \mathbf{1}\{x_{j}^{(i)} = 1, y^{(i)} = b\} + 1}{\sum_{i=1}^{m} \mathbf{1}\{y^{i} = b\} + 2}$$

In practice we don't apply Laplace smoothing to $\phi_y = p(y = 1)$, which is greater than 0.

Naïve Bayes Summarv

Naïve Bayes (NB) assumption

 x_i 's are conditionally independent given y:

$$p(x_1,\ldots,x_n|y) = \prod_{i=1}^n p(x_i|y)$$

Different event models



Nulti-variate Bernoulli model: represent document of vocab size *n* as *n* independent Bernoulli trails

Multinomial event model: represent document of N words as $x = \{x_1, ..., x_n\}$ where $x_i \in \{1, ..., K\}$. (not covered)

Homework

- Programming Assignment 1 late submission.
- TA sessions